Doubly Structured Polar Decompositions and Algebraic Riccati Equations

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Joint work with Ulric Kintzel.



Overview

(G, H)-Polar Decompositions and AREs

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(G, H)-Polar Decompositions

Nonsymmetric Algebraic Riccat Equations

Numerical Solution

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- Application: Procrustes Problems
- Existence Results
- 2 Nonsymmetric Algebraic Riccati Equations

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 - The Matrix Sign Function

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(G, H)-Polar Decompositions and AREs

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Polar decomposition in \mathbb{C}^n

Let $A \in \mathbb{C}^{n \times n}$, then

$$A = UM, \quad U^{-1} = U^*$$
 (unitary), $M = M^* \ge 0,$

is called a polar decomposition of A.

Note: any matrix admits a polar decomposition as

$$A = (UV^*)(V\Sigma V^*),$$

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where $A = U\Sigma V^*$ is the SVD of A.



Generalization of polar decompositions in finite-dim. indefinite inner product spaces

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Given $A \in \mathbb{C}^{n \times n}$, $H = H^* \in \mathbb{C}^{n \times n}$ nonsingular, and the corresponding (indefinite) inner product

$$\langle x, y \rangle_H := \langle Hx, y \rangle$$

where $\langle ., . \rangle$ is the standard unitary inner product, then the *H*-adjoint of *M*, i.e., the adjoint of *M* w.r.t. $\langle ., . \rangle_H$, is $M^H = H^{-1}M^*H$.



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H-polar decomposition

$$A = UM$$
, $U^{-1} = U^H$ (H-unitary), $M = M^H$.



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H-polar decomposition

$$A = UM$$
, $U^{-1} = U^H$ (*H*-unitary), $M = M^H$.

Note: not all $A \in \mathbb{C}^{n \times n}$ admit an *H*-polar decomposition! Existence results:

- Bolshakov, van der Mee, Ran, Reichstein, Rodman (1997)
- Lins, Meade, Mehl, Rodman (2001)
- Kintzel (2003,2005)
- Mehl, Ran, Rodman (2006)



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(G, H)-polar decomposition [KINTZEL 2003/2005]

Let $H = H^*, G = G^*$ nonsingular, then

$$A = UM, \quad U^{-1} = U^G = U^H, \ M = M^G = M^H,$$

is a (G, H)-polar decomposition. In this case

- U is (G, H)-unitary,
- M is (G, H)-selfadjoint.

(G, H)-polar decomposition is H-semidefinite if $HM \ge 0$.



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Unitary (Orthogonal) Procrustes Problems

Given $C, B \in \mathbb{C}^{m \times n}$, find $U \in \mathbb{C}^{m \times m}$ unitary minimizing

$$\|UC-B\|_F.$$

In other words, for $C = [c_1, \ldots, c_n], B = [b_1, \ldots, b_n]$, minimize

$$\sum_{k=1}^n \langle Uc_k - b_k, Uc_k - b_k \rangle.$$

under the constraint $U^{-1} = U^*$.

Solution: U = unitary factor of polar decomposition $BC^* = UM$.



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(G, H)-Isometric Procrustes Problem [KINTZEL 2003/2005]

Given $C = [c_1, \ldots, c_n], B = [b_1, \ldots, b_n] \in \mathbb{C}^{m \times n}$, find $U \in \mathbb{C}^{m \times m}$ optimizing

$$\sum_{k=1}^{''} \langle Uc_k - b_k, Uc_k - b_k \rangle_H$$

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under the constraint $U^{-1} = U^G = U^H$.



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(*G*, *H*)-Isometric Procrustes Problem [KINTZEL 2003/2005]

Given $C = [c_1, \ldots, c_n], B = [b_1, \ldots, b_n] \in \mathbb{C}^{m \times n}$, find $U \in \mathbb{C}^{m \times m}$ optimizing

$$\sum_{k=1}^{''} \langle Uc_k - b_k, Uc_k - b_k \rangle_H$$

under the constraint $U^{-1} = U^G = U^H$.

Solution (for $H^{-1}G = \mu^2 G^{-1}H$, $\mu \in \mathbb{R} \setminus \{0\}$):

existence \iff there exists an *H*-semidefinite (*G*, *H*)-polar decomposition

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A := BC^*H + G^{-1}HBC^*G = UM.
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Then, the optimizing U is just the (G, H)-unitary factor.



(G, H)-Polar Decompositions and AREs

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(G, H)-Polar Decomposition

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Recall: want A = UM so that $U^{-1} = U^G = U^H$ and $M = M^G = M^H$.

Necessary condition

$$A^H = A^G$$
, as $A^H = M^H U^H = M^G U^G = A^G$.

Note: if $\lambda H - G \in \mathbb{C}^{n \times n}$ is non-defective Hermitian matrix pencil, such matrices impose a "normal" form of (A, H, G):

 $(S^{-1}AS, S^*HS, S^*GS) = (A_1 \oplus \ldots \oplus A_k, H_1 \oplus \ldots \oplus H_k, G_1 \oplus \ldots \oplus G_k),$

where

for real eigenvalues μ_j , $j = 1, \ldots, r$, of $\lambda H - G$:

$$A_j \in \mathbb{C}^{p_j \times p_j}, \quad H_j = I_{p_j - q_j} \oplus -I_{q_j}, \quad G_j = \mu_j (I_{p_j - q_j} \oplus -I_{q_j}),$$

for non-real eigenvalues μ_j , $j = r + 1, \dots, \ell$, of $\lambda H - G$:

$$A_{j} = \begin{bmatrix} A_{j,1} & \\ & A_{j,2} \end{bmatrix} \in \mathbb{C}^{2p_{j} \times 2p_{j}}, \quad H_{j} = \begin{bmatrix} & I_{p_{j}} \\ I_{p_{j}} \end{bmatrix}, \quad G_{j} = \begin{bmatrix} & \overline{\mu_{j}} I_{p_{j}} \\ & \mu_{p_{j}} \end{bmatrix}.$$



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Recall: want A = UM so that $U^{-1} = U^G = U^H$ and $M = M^G = M^H$.

Necessary and sufficient condition

If $\lambda H - G \in \mathbb{C}^{n \times n}$ is non-defective Hermitian matrix pencil, then $A^H = A^G$ admits a (G, H) polar decomposition

in the "normal" form of A,

1 all blocks A_j corresponding to real eigenvalues of $\lambda H - G$ admit an H_j -polar decomposition,

 \Leftrightarrow

2 all blocks A_j corresponding to non-real eigenvalues of $\lambda H - G$ satisfy nonsymmetric algebraic Riccati equations (nARE)

$$A_{j,1}=U_jA_{j,2}^*U_j,$$

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with $U_j \in \mathbb{C}^{p_j \times p_j}$ nonsingular.



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(G, H)-Polar Decompositions and AREs

Nonsymmetric Algebraic Riccati Equations

General form of nARE:

$$0 = A + DX - XC - XBX,$$

where $A, B^* \in \mathbb{C}^{n \times m}$, $C \in \mathbb{C}^{m \times m}$, $D \in \mathbb{C}^{n \times n}$ are given and $X \in \mathbb{C}^{n \times m}$ is unknown. Corresponding data matrix:

$$K = \left[\begin{array}{cc} C & B \\ A & D \end{array} \right].$$

Well-known:

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Well-known:

 $\begin{array}{c} X \text{ is a solution} \\ \longleftrightarrow \\ \operatorname{range}\left(\begin{bmatrix} I \\ X \end{bmatrix} \right) \text{ is an } K \text{-invariant subspace corresponding to} \\ \Lambda(C + BX). \end{array}$



Nonsymmetric Algebraic Riccati Equations

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Here: nARE with zero Sylvester part (nAREzS)

$$0=A-XBX,$$

where $A, B \in \mathbb{C}^{n \times n}$ are given and $X \in \mathbb{C}^{n \times n}$ is unknown. Corresponding data matrix:

$$K = \left[\begin{array}{c} B \\ A \end{array} \right].$$

Well-known:

X is a solution

range $\binom{I}{X}$ is an K-invariant subspace corresponding to $\Lambda(BX)$.

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Of course, with X, also Y = -X is a solution!



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Recall: for (G, H)-polar decomposition, need invertible solution! Trivial consequence: rank (A) = rank (B) is necessary condition.

heorem

Let $A, B \in \mathbb{C}^{n \times n}$. Then there exists a nonsingular matrix $X \in \mathbb{C}^{n \times n}$ solution of the nAREzS

0 = A - XBX

 \iff there exists a matrix square root $M \in \mathbb{C}^{n \times n}$ of *BA* with

ker $A = \ker M$ and ker $B^* = \ker M^*$.

Proof:

[⇒] Let X be a nonsingular solution. For $M = X^{-1}A = BX$: $BA = M^2$ as well as ker $A = \ker M$. Since $X^*B^* = M^*$, we also have ker $B^* = \ker M^*$. [⇐] if rank (A) = rank (B) = n, then $X = AM^{-1}$ is a solution. Otherwise, construct suitable generalized inverse of M.

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Many possibilities:

use explicit solution $X = AM^{-1}$ (matrix square root of *BA* can be computed without forming product *BA* [B./FASSBENDER 2001]),

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or special versions of

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- Schur vector method [LAUB 1979],
- Newton's method [DEMMEL 1987],
- sign function method,



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Compute Schur decomposition

$$\begin{bmatrix} B \\ A \end{bmatrix} \begin{bmatrix} U_1 & U_2 \\ V_1 & V_2 \end{bmatrix} = \begin{bmatrix} U_1 & U_2 \\ V_1 & V_2 \end{bmatrix} \begin{bmatrix} T_1 & S \\ T_2 \end{bmatrix}.$$

Then: if U_1 is invertible, then

$$X = \pm V_1 U_1^{-1}$$

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are solutions to 0 = A - XBX.

Open questions:

- Under which conditions is U₁ nonsingular?
- Under which conditions is X nonsingular? (Obviously, if rank (V₁) = n, but ...)
- How to exploit zero blocks in K?



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- Under which conditions is X nonsingular? (Obviously, if rank (V₁) = n, but ...)
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$$\begin{bmatrix} B \\ A \end{bmatrix} \begin{bmatrix} U_1 & U_2 \\ V_1 & V_2 \end{bmatrix} = \begin{bmatrix} U_1 & U_2 \\ V_1 & V_2 \end{bmatrix} \begin{bmatrix} T_1 & S \\ T_2 \end{bmatrix}.$$

Then: if U_1 is invertible, then

$$X = \pm V_1 U_1^{-1}$$

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are solutions to 0 = A - XBX.

Open questions:

- Under which conditions is *U*¹ nonsingular?
- Under which conditions is X nonsingular? (Obviously, if rank (V₁) = n, but ...)

■ How to exploit zero blocks in *K*?



(G, H)-Polar Decompositions and AREs

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Numerical Solution of nAREzS Newton's Method

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For $\mathcal{R}(X) = A - XBX$, Newton-Kantorovich method

$$\mathcal{R}'_{X_j}(Z_j) = -\mathcal{R}(X_j), \quad X_{j+1} = X_j + Z_j,$$

can be written as

- Solve Sylvester equation $(X_jB)Z_j + Z_j(BX_j) = A X_jBX_j$.
- Set $X_{j+1} = X_j + Z_j$.

Conjecture: convergence from $X_0 = I_n$ for $\Lambda(AB) \cap \mathbb{R}_0^- = \emptyset$.



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Definition

For $Z \in \mathbb{R}^{n \times n}$ with $\Lambda(Z) \cap i\mathbb{R} = \emptyset$ and Jordan canonical form

$$Z = S^{-1} \left[\begin{array}{cc} J^+ & 0 \\ 0 & J^- \end{array} \right] S$$

the matrix sign function is

$$\operatorname{sign}\left(Z\right) := S \left[\begin{array}{cc} I_k & 0 \\ 0 & -I_{n-k} \end{array} \right] S^{-1}$$



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Computation of sign (Z)

sign (Z) is root of $I_n \implies$ use Newton's method to compute it:

$$Z_0 \leftarrow Z, \qquad Z_{j+1} \leftarrow \frac{1}{2} \left(Z_j + Z_j^{-1} \right), \qquad j = 1, 2, \dots$$

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 $\Rightarrow \quad \operatorname{sign}(Z) = \lim_{j \to \infty} Z_j.$



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$$\Rightarrow \quad \operatorname{sign}(Z) = \lim_{j \to \infty} Z_j.$$

Computation of sign (Z)

Application to
$$K = \begin{bmatrix} A \end{bmatrix}$$
 yields for $A_0 = A, B_0 = B$:
 $A_{j+1} \leftarrow \frac{1}{2} \left(A_j + B_j^{-1} \right), \quad B_{j+1} \leftarrow \frac{1}{2} \left(B_j + A_j^{-1} \right),$
for $j = 1, 2, \dots$ and $X = \lim_{j \to \infty} A_j$ if $\Lambda (AB) \cap \mathbb{R}_0^- = \emptyset.$



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- (G, H)-polar decompositions can be used to solve generalized Procrustes problems in non-Euclidian geometries — useful in psychometrics/multidimensional scaling.
- Construction of (G, H)-polar decompositions leads to nonsymmetric algebraic Riccati equations with zero Sylvester (linear) part.
- Efficient numerical algorithms for nAREzS not yet fully developed work in progress!

Thanks for your attention!